

Intracellular transportation involves multiple molecular proteins working together in coordination. These proteins are of different t i.e. they have different chemical as well as physical properties. Understanding transport properties of these molecules individua well as of their ensembles help understand the underlying mechanism of genesis of neurodegenerative diseases. Various studies have been carried out to characterize motion of a molecular cargo in-vivo as well as in-vitro. Analytical approache Monte-Carlo Simulations used to study how motor-proteins coordinate the transportation of a cargo are either too simplistic in r or require high computational power, at the same time do not capture the rare event scenarios. To overcome these challenges, analytical approaches have proven to be quite effective for studying biologically relevant quantities while enabling us to observ occurrence of rear events.

So far, semi-analytical approaches have been developed for studying the transportation of a shared cargo with ensemble of protein of only one species type. In these approaches, the movement of cargo is restricted to only one direction on microtubule la Further work has been done to extend this approach to the case when some of the motors are mutated while still being restrict one directional motion of cargo. These approaches, while being less computationally intensive compared to Monte-Carlo simula produce comparable results to any other techniques available for simulating single species, unidirectional transportation. They also insights about some of the rare events occurring which other techniques fail to capture. This provides the motivation to develop since a second structure of the rare events occurring which other techniques fail to capture. approach and extend the existing semi-analytical framework for bi-direction intracellular transportation. We develop a more generalized approach which enables us to study the transportation of cargo by an ensemble of two species r molecules. This enables us to study biologically relevant quantities such as average run-length and average velocity of the molecule while taking into account bi-directional motion of ensemble. Added direction of motion and forces gives rise to the char behavior of ensemble and makes the extension of the single species, unidirectional case to a two species, bi-directional case a trivial task.

We begin by defining the transition probabilities of change in absolute configurations of ensemble. Since the number of abs configurations of an ensemble, and hence their combinations, are infinite, this makes the problem intractable. We determine equivalence class of various absolute configuration by using the relative configurations defined by the relative distances of the m We prove that the number of such relative configurations are finite. We further prove that several biologically relevant quantities c calculated using the relative configurations. The technique has been instantiated by calculating these quantities for an ensemble motors consisting of Kinesin and Dynein and some of the key results are presented.



• Real nature of bi-directional ensemble explored

forces

Bi-Directional Transport Properties of 2-Species Molecular Motor Ensemble Rachit Shrivastava^a, Sivaraman Rajaganapathy^a, Shreyas Bhaban^a, Thomas Hays^b and Murti Salapaka^a

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ABSTRACT

	FUTURE DIRE
n of properties of bi- directional motion ection, direction of the two stalling	 More realistic Dynein models with varied Both forward and backward moving probincorporated Comparison with Monte Carlo simulation Simulating models which represent in-viving Temperature, ATP Concentration etc. and direction of force as soon as direction of the source of the

	CON	ΛΡυτατιά	DNS ^[1,2] AN
types, ally as es and nature semi- ve the motor attice. ted to ations, so give similar motor cargo nge in a non-	CONPARAMETSpring ConstantStep SizeStall ForceRest Stalk LengthRate of attachmentUnloaded Run LengthType 1 species \rightarrow Infinite dimensional $\frac{\partial}{\partial t} P_{rel}(\sigma, t) = -P_{rel}(\sigma, t)$ • Projection possible	Image: Application of the second state of finite Terms Terms $(\dots \ 0 \ 0 \ 1 \ \dots \ 1 \ 0 \ 1)$ $(\dots \ 1 \ 0 \ 1)$ $t) \sum_{\sigma' \in Q} \lambda_{rel}(\sigma', \sigma)$ because of finite	DNS ^[1,2] AN UNITS pN/nm nm pN nm per motor per set nm 1 0 1) 0 0 0/ of configuration f configuration
ine an notors. can be ible of	 Probabilities of each λ_{rel} (σ', σ) are the tattachment and deta Type 1 species can s Both species have d 	relative configu ransition rates fr achment rates of tep only in forwa ifferent load forc	rations are found u om one relative co both type of spec and direction and ty e dependent stepp
Avera Avera 2 0.004 For Vith Unidire	age Velocity	-10 E -20 .u -30 -30 -40 -60 -60 0.005 Ensemble simila • Typical valu for 1 Kinesi	Average Runleng 0.01 0.07 Fload in nN e of two motor mol r parameters but of directionality ues of run length at in 1 Dynein Ensem
CTIO	NS		

motors. BMC biophysics (2013)

step length to be incorporated pabilities of Dynein to be

ns and experimental results vo conditions with changes in d with an option of reversal of movement changes



ND PARAMETERS USED³

	KINESIN	DYNEIN
	0.32	0.32
	8	8
	5	1.25
	110	50
econd	5	5
		689



 $(0 \ 0 \ 0 \ 1)$

Converted to a finite dimensional Markov model by taking projections and defining equivalence class of relative configurations

$$P_{rel}(\sigma',t) \Longrightarrow \frac{d}{dt}P(t) = AP(t) \implies P(t) = e^{A(t-t_0)}P(t_0)$$

e configurations which is a consequence of finite extent using the above master equation

onfiguration to other. Rates are computed using stepping, cies

ype 2 species can only step in backward direction ping and detachment rates

MULATION RESULTS



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