

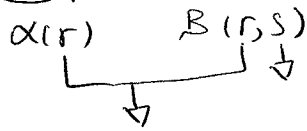
stability of time-varying systems

$$\dot{x} = f(x, t)$$

↑ time appears explicitly in the state equation.

Linear systems: $\boxed{\dot{x} = A(t)x}$

Class K, K_∞, K_L functions: (are scalar valued)



System theoretic interpretation of our symbols:

$r: \|x_0\|$, $s: t - t_0$

A Continuous function $\alpha: [0, \infty) \rightarrow [0, \infty)$ is a class K (function: scalar argument & scalar valued!)

function if:

- 1°) $\alpha(0) = 0$
- 2°) It's strictly increasing

If in addition to 1° & 2°: $\alpha(r) \xrightarrow{r \rightarrow \infty} +\infty$ then class K_∞ function. α is a

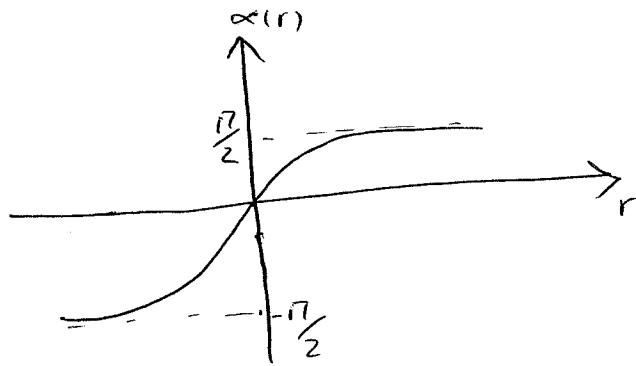
EX 1: $\alpha(r) = r^c$; $c > 0$

$\boxed{\alpha(0) = 0}$

$\frac{d\alpha}{dr} = cr^{c-1} > 0 \rightarrow$ strictly increasing

$\lim_{r \rightarrow \infty} r^c = \infty \rightarrow \boxed{K_\infty}$

Ex2: $\alpha(r) = a \tan r$



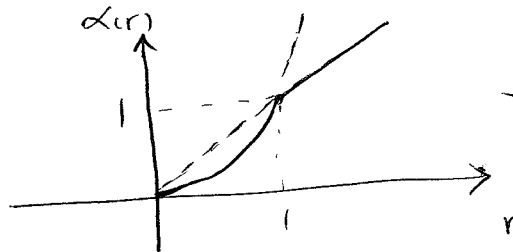
$\rightarrow \alpha(0) = 0$

$\frac{d\alpha}{dr} > 0 = \frac{1}{1+r^2}$

$\left. \begin{array}{l} \rightarrow \text{Class K} \\ \text{but not } K_\infty! \end{array} \right\}$

Ex3

$\alpha(r) = \min(r, r^2)$



$\rightarrow K_\infty$

So, K & K_∞ functions don't need to be differentiable!

$B(r, s) : [0, \infty) \times [0, \infty) \rightarrow [0, \infty)$

1°) $B(\cdot, s) : \text{Class K function}$

(For fixed 's', $B(\cdot, s)$ is class K)

2°) $B(r, \cdot)$ is decreasing and $B(r, s) \xrightarrow{s \rightarrow \infty} 0$ for any fixed r.

Ex4 $B(r, s) = Kr^c e^{-as}$, $c, K, a > 0$

\rightarrow KL function

Ex 5 $B(r,s) = \frac{r}{Krs+1}$, $K > 0$

$B(0,s) = 0 \rightarrow$ first condition.

Checking the second condition: Is it increasing?

$\frac{dB}{dr} = \frac{Krs+1 - Kr^2}{(Krs+1)^2} > 0 \rightarrow$ Class K
 "strictly increasing" (for fixed s)
 (monotonically)

$\rightarrow B(r, \cdot)$, for fixed r , is decreasing and goes to 0 as $s \rightarrow \infty$

\Rightarrow K_L Function

$\bar{x} = 0$ is a stable eq. point of $\dot{x} = f(x,t)$ iff
 $\forall \epsilon > 0$, there is $\delta = \delta(\epsilon, t_0)$ s.t. $\|x(t_0)\| < \delta \rightarrow \|x(t)\| < \epsilon$
 \downarrow
 $\varphi(x(t_0), t_0)$

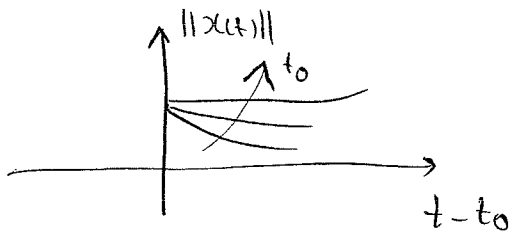
If $\delta = \delta(\epsilon)$ (doesn't depend on t_0) then uniform stability!

EX: $\dot{x} = -\frac{1}{1+t} x \Rightarrow x(t) = \frac{(1+t_0)}{1+t} x(t_0), t \geq t_0$

\Rightarrow origin is \checkmark uniformly stable because $\rightarrow \|x(t)\| \leq \|x(t_0)\|$ for all $t \geq t_0$

Also, $\lim_{t \rightarrow \infty} \|x(t)\| = 0 \rightarrow$ asymptotically stable!

Is it uniformly asymptotically stable?



Is the rate of convergence going to be different when we change t_0 ?

$$\Rightarrow x(t) = \frac{1}{1 + \frac{t-t_0}{1+t_0}} x(t_0) \rightarrow t_0 \uparrow, \text{ rate of convergence } \uparrow$$

→ not uniformly asymptotically stable!

So, no uniform convergence rate (increases) with t_0

Stability characterization in terms of K & K_L functions:

The origin of $\dot{x} = f(x, t)$ is

1°) uniformly stable if there is a class K function $\alpha(\cdot)$ and a constant $c > 0$

s.t. $\|x(t)\| \leq \alpha(\|x_0\|)$ for all $t \geq t_0$ and all $x(t_0)$ with $\|x(t_0)\| < c$

2°) uniformly asymptotically stable if there is a class K_L function $B(\cdot, \cdot)$ and a constant c s.t.

$\|x(t)\| \leq B(\|x(t_0)\|, t-t_0)$ for all $t \geq t_0$ and all $x(t_0)$ with $\|x(t_0)\| < c$

Lyapunov functions for time-varying systems:

Ex: $\dot{x} = A(t)x$

$$\Rightarrow V(x) = x^T P(t) x$$

Ex $\dot{x} = f(x, t)$

$$V(x, t) \rightarrow \dot{V} = \frac{\partial V}{\partial t} + \frac{\partial V}{\partial x} \underbrace{f(x, t)}_{\dot{x}}$$

Comparison Functions

A big picture overview of what's coming on Tuesday?

$$\alpha_1(\|x\|) \leq V(x, t) \leq \alpha_2(\|x\|)$$

where α_1, α_2 are class K (or K_∞) functions!

Aside Ex: $V(x) = x^T P x$; $P \neq P(t)$

$$\lambda_{\min}(P) \|x\|^2 \leq x^T P x \leq \lambda_{\max}(P) \|x\|^2$$

$$\rightarrow \alpha_1(r) = \lambda_{\min}(P) r^2, \quad \alpha_2(r) = \lambda_{\max}(P) r^2 \rightarrow$$

which are K_∞ if P_1 is PD!