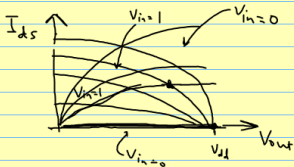
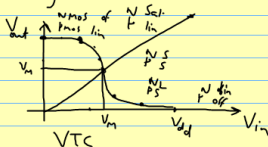
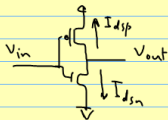


Inverter Analysis



V_m = switching threshold
(trip point)

$$V_{in} = V_{out}$$

$$V_M$$

$$I_{dsn} = -I_{dsp}$$

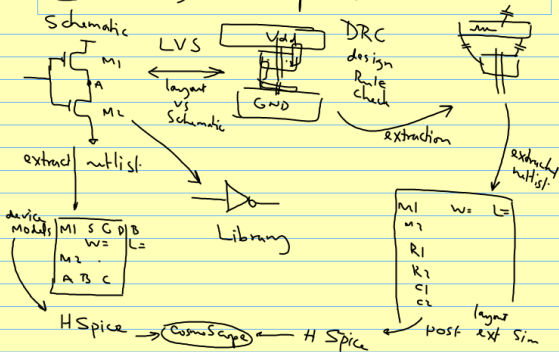
$$\underbrace{\left(\mu C_{ox} \frac{W}{L}\right)}_n \left(V_M - V_{tn} - \frac{V_{dsatn}}{2} \right) \cdot V_{dsatn} = - k_p \left(V_M - V_{dd} - V_{tp} - \frac{V_{dsatp}}{2} \right) \cdot V_{dsatp}$$

$$V_M - V_{tn} - \frac{V_{dsatn}}{2} = - \underbrace{\left(\frac{k_p V_{dsatp}}{k_n V_{dsatn}} \right)}_r \cdot (V_M - \dots)$$

$$\underline{V_M} = \frac{V_{tn} + \frac{V_{dsatn}}{2} + r \left(V_{tp} + \frac{V_{dsatp}}{2} + V_{dd} \right)}{1+r}$$

$$\underline{r \approx 1} \text{ and } V_{dd} \text{ large} \Rightarrow \underline{V_M} \approx \frac{r}{1+r} V_{dd}$$

[Design Steps]

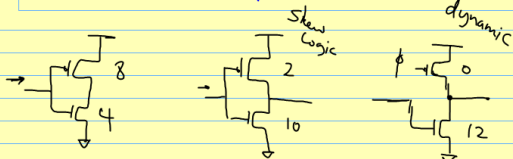


$$V_m \quad \text{and} \quad r=1 \quad \left(\begin{array}{l} \text{b/c want} \\ V_m = \frac{1}{2} V_{dd} \end{array} \right)$$

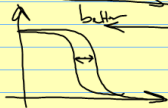
$$r = \frac{k_p V_{dsatp}}{k_n V_{dsatn}} = \frac{\left(\cancel{\mu_{ox}} \cancel{\frac{W}{L}} \right)_p}{\left(\cancel{\mu_{ox}} \cancel{\frac{W}{L}} \right)_n} \cdot \frac{V_{dsatp}}{V_{dsatn}} = 1$$

$$\frac{W_p}{W_n} = \frac{\mu_n}{\mu_p} \cdot \frac{\cancel{V_{dsatp}}}{\cancel{V_{dsatp}}} \approx 2$$

NOISE vs Speed



better ← Noise
 Speed → better
 ← better Power



$$\text{delay} \propto \frac{1}{w}$$