

Lecture 15: Systems with inputs

- Input types
 - ★ Additive inputs
 - ★ Boundary inputs
- Input-output mappings
 - ★ Transfer function
 - ★ Frequency response
 - ★ Impulse response
- Abstract evolution equation for boundary control systems
 - ★ Objective: bring system into a form that resembles standard formulation
- Two point boundary value problems

Additive inputs

- Example: diffusion equation on $L_2[-1, 1]$ with Dirichlet BCs

$$\phi_t(x, t) = \phi_{xx}(x, t) + u(x, t)$$

$$\phi(x, 0) = \phi_0(x)$$

$$\phi(\pm 1, t) = 0$$

- Abstract evolution equation

$$\psi_t(t) = \mathcal{A}\psi(t) + u(t)$$

$$\mathcal{A} = \frac{d^2}{dx^2}, \quad \mathcal{D}(\mathcal{A}) = \{f \in L_2[-1, 1], f'' \in L_2[-1, 1], f(\pm 1) = 0\}$$

- Solution

$$\psi(t) = \mathcal{T}(t)\psi(0) + \int_0^t \mathcal{T}(t - \tau)u(\tau) d\tau$$

$\mathcal{T}(t)$: C_0 -semigroup generated by \mathcal{A}

Input-output maps

$$\dot{\psi}(t) = \mathcal{A}\psi(t) + \mathcal{B}u(t)$$

$$\phi(t) = \mathcal{C}\psi(t)$$

- Underlying operators:

$$\begin{cases} \mathcal{A}: \mathbb{H} \supset \mathcal{D}(\mathcal{A}) \longrightarrow \mathbb{H} \\ \mathcal{B}: \mathbb{U} \longrightarrow \mathbb{H} \\ \mathcal{C}: \mathbb{H} \longrightarrow \mathbb{Y} \end{cases}$$
- Input-output mapping

$$\phi(t) = [\mathcal{H}u](t) = \int_0^t \mathcal{C}\mathcal{T}(t-\tau)\mathcal{B}u(\tau) d\tau$$

- ★ Impulse response

$$\mathcal{H}(t) = (\mathcal{C}\mathcal{T}(t)\mathcal{B})\mathbf{1}(t)$$

- ★ Transfer function

$$\mathcal{H}(s) = \mathcal{C}(sI - \mathcal{A})^{-1}\mathcal{B}$$

- ★ Frequency response

$$\mathcal{H}(j\omega) = \mathcal{C}(j\omega I - \mathcal{A})^{-1}\mathcal{B}$$

An example

$$\left. \begin{array}{l} \phi_t(x, t) = \phi_{xx}(x, t) + u(x, t) \\ \phi(\pm 1, t) = 0 \end{array} \right\} \xrightarrow[\text{transform}]{\text{Laplace}} \left\{ \begin{array}{l} \phi''(x, s) = s\phi(x, s) - u(x, s) \\ \phi(\pm 1, s) = 0 \end{array} \right.$$

- Spatial realization of $\mathcal{H}(s)$ (with $\psi_1 = \phi$, $\psi_2 = \phi'$)

$$\begin{bmatrix} \psi_1'(x, s) \\ \psi_2'(x, s) \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ s & 0 \end{bmatrix} \begin{bmatrix} \psi_1(x, s) \\ \psi_2(x, s) \end{bmatrix} + \begin{bmatrix} 0 \\ -1 \end{bmatrix} u(x, s)$$

$$\phi(x, s) = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} \psi_1(x, s) \\ \psi_2(x, s) \end{bmatrix}$$

$$0 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \psi_1(-1, s) \\ \psi_2(-1, s) \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} \psi_1(1, s) \\ \psi_2(1, s) \end{bmatrix}$$

- Two point boundary value problem

$$\psi'(x) = A(x)\psi(x) + B(x)u(x)$$

$$\phi(x) = C(x)\psi(x)$$

$$0 = N_a\psi(a) + N_b\psi(b)$$

Boundary control

- Example: diffusion equation on $L_2[-1, 1]$

$$\left. \begin{aligned} \phi_t(x, t) &= \phi_{xx}(x, t) + d(x, t) \\ \phi(-1, t) &= u(t) \\ \phi(+1, t) &= 0 \end{aligned} \right\} \xrightarrow{\text{Laplace transform}} \left\{ \begin{aligned} \phi''(x, s) &= s\phi(x, s) - d(x, s) \\ \phi(-1, s) &= u(s) \\ \phi(+1, s) &= 0 \end{aligned} \right.$$

- Spatial realization of $\mathcal{H}(s)$ (with $\psi_1 = \phi$, $\psi_2 = \phi'$)

$$\begin{bmatrix} \psi_1'(x, s) \\ \psi_2'(x, s) \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ s & 0 \end{bmatrix} \begin{bmatrix} \psi_1(x, s) \\ \psi_2(x, s) \end{bmatrix} + \begin{bmatrix} 0 \\ -1 \end{bmatrix} d(x, s)$$

$$\phi(x, s) = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} \psi_1(x, s) \\ \psi_2(x, s) \end{bmatrix}$$

$$\begin{bmatrix} u(s) \\ 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \psi_1(-1, s) \\ \psi_2(-1, s) \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} \psi_1(1, s) \\ \psi_2(1, s) \end{bmatrix}$$

- Two point boundary value problem

$$\psi'(x) = A(x)\psi(x) + B(x)d(x)$$

$$\phi(x) = C(x)\psi(x)$$

$$\nu = N_a\psi(a) + N_b\psi(b)$$

Abstract evolution equation for systems with boundary inputs

$$\phi_t(x, t) = \phi_{xx}(x, t) + d(x, t)$$

$$\phi(-1, t) = u(t)$$

$$\phi(+1, t) = 0$$

- Problem: control doesn't enter additively into the equation
- Coordinate transformation

$$\psi(x, t) = \phi(x, t) - f(x) u(t)$$

- ★ Choose $f(x)$ to obtain homogeneous boundary conditions $\psi(\pm 1, t) = 0$
- ★ Many possible choices

Conditions for selection of f :

$$\{f(-1) = 1, f(1) = 0\} \xrightarrow{\text{simple option}} f(x) = \frac{1-x}{2}$$

- In new coordinates:

$$\phi_t(x, t) = \phi_{xx}(x, t) + d(x, t)$$

$$\phi(-1, t) = u(t)$$

$$\phi(+1, t) = 0$$

$$\downarrow \phi(x, t) = \psi(x, t) + f(x) u(t)$$

$$\psi_t(x, t) + f(x) \dot{u}(t) = \psi_{xx}(x, t) + f''(x) u(t) + d(x, t)$$

$$\psi(\pm 1, t) = 0$$



- New input: $v(t) = \dot{u}(t)$

$$\frac{d}{dt} \begin{bmatrix} \psi(t) \\ u(t) \end{bmatrix} = \begin{bmatrix} \mathcal{A}_0 & f'' \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \psi(t) \\ u(t) \end{bmatrix} + \begin{bmatrix} I \\ 0 \end{bmatrix} d(t) + \begin{bmatrix} -f \\ I \end{bmatrix} v(t)$$

$$\phi(t) = \begin{bmatrix} I & f \end{bmatrix} \begin{bmatrix} \psi(t) \\ u(t) \end{bmatrix}$$

$$\mathcal{A}_0 = \frac{d^2}{dx^2}, \quad \mathcal{D}(\mathcal{A}_0) = \{f \in L_2[-1, 1], f'' \in L_2[-1, 1], f(\pm 1) = 0\}$$

Two point boundary value problems

$$\psi'(x) = A(x) \psi(x) + B(x) d(x)$$

$$\phi(x) = C(x) \psi(x)$$

$$\nu = N_a \psi(a) + N_b \psi(b)$$

- Solution:

$$\phi(x) = C(x) \Phi(x, a) (N_a + N_b \Phi(b, a))^{-1} \nu + C(x) \int_a^x \Phi(x, \xi) B(\xi) d(\xi) d\xi -$$

$$C(x) \Phi(x, a) (N_a + N_b \Phi(b, a))^{-1} N_b \int_a^b \Phi(b, \xi) B(\xi) d(\xi) d\xi$$



$\Phi(x, \xi)$: the state transition matrix of $A(x)$

$$\frac{d\Phi(x, \xi)}{dx} = A(x) \Phi(x, \xi), \quad \Phi(\xi, \xi) = I$$

For systems with $A \neq A(x)$:

$$\Phi(x, \xi) = e^{A(x-\xi)}$$

Examples

- Heat equation with boundary actuation

$$\phi_t(x, t) = \phi_{xx}(x, t)$$

$$\phi(-1, t) = u(t)$$

$$\phi(+1, t) = 0$$

↓ Laplace transform

$$\begin{bmatrix} \psi'_1(x, s) \\ \psi'_2(x, s) \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ s & 0 \end{bmatrix} \begin{bmatrix} \psi_1(x, s) \\ \psi_2(x, s) \end{bmatrix}$$

$$\phi(x, s) = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} \psi_1(x, s) \\ \psi_2(x, s) \end{bmatrix}$$

$$\begin{bmatrix} u(s) \\ 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \psi_1(-1, s) \\ \psi_2(-1, s) \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} \psi_1(1, s) \\ \psi_2(1, s) \end{bmatrix}$$

$$\begin{aligned} \phi(x, s) &= C e^{A(s)(x-a)} (N_a + N_b e^{A(s)(b-a)})^{-1} \nu(s) \\ &= \frac{\sinh(\sqrt{s}(1-x))}{\sinh(2\sqrt{s})} u(s) \\ &= \left(\frac{1-x}{2} - \sum_{n=1}^{\infty} \frac{2}{n\pi} \frac{s}{s + (n\pi/2)^2} v_n(x) \right) u(s) \end{aligned}$$

- Eigenvalue problem for streamwise constant linearized NS equations

$$\text{Orr-Sommerfeld: } \begin{cases} \mathcal{L} \psi_{os} = \lambda_{os} \psi_{os}, & \psi_{os}(\pm 1) = \psi'_{os}(\pm 1) = 0 \\ \mathcal{S} u_{os} = \lambda_{os} u_{os} - \mathcal{C}_p \psi_{os}, & u_{os}(\pm 1) = 0 \end{cases}$$

↓

$$\begin{cases} \Delta^2 \psi_{os} = \lambda_{os} \Delta \psi_{os}, & \psi_{os}(\pm 1) = \psi'_{os}(\pm 1) = 0 \\ \Delta u_{os} = \lambda_{os} u_{os} - jk_z U'(y) \psi_{os}, & u_{os}(\pm 1) = 0 \end{cases}$$



Two point boundary value problem for u_{os} :

$$\begin{bmatrix} x'_1(y, k_z) \\ x'_2(y, k_z) \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ \lambda_{os} + k_z^2 & 0 \end{bmatrix} \begin{bmatrix} x_1(y, k_z) \\ x_2(y, k_z) \end{bmatrix} + \begin{bmatrix} 0 \\ -jk_z U'(y) \end{bmatrix} \psi_{os}(y, k_z)$$

$$u_{os}(y, k_z) = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} x_1(y, k_z) \\ x_2(y, k_z) \end{bmatrix}$$

$$0 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1(-1, k_z) \\ x_2(-1, k_z) \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x_1(1, k_z) \\ x_2(1, k_z) \end{bmatrix}$$