

Systems with inputs

Two input types:

- * Additive inputs

- * Boundary inputs

Heat equation example for additive inputs

$$\phi_t(x,t) = \phi_{xx}(x,t) + u(x,t)$$

$$\phi(x,0) = \phi_0(x)$$

$$\phi(\pm 1, t) = 0$$

Abstract evolution equation

$$\Psi_t(t) = A\Psi(t) + u(t)$$

$$A = \frac{d^2}{dx^2}, \quad D(A) = \{f \in L_2[-1,1], f'' \in L_2[-1,1], f(\pm 1) = 0\}$$

Solution $\Psi(t) = T(t)\phi(0) + \int_0^t T(t-\tau)u(\tau)d\tau$

$$\phi(x,t) = \sum_{n=1}^{+\infty} a_n(t) v_n(x)$$

$$[T(t)\phi(0)](x) = \sum_{n=1}^{+\infty} e^{\lambda_n t} v_n(x) \langle v_n, \phi(0) \rangle$$

$$\dot{a}_n(t) = \lambda_n a_n(t)$$

$$\hookrightarrow -\left(\frac{n\pi}{2}\right)^2$$

$$\int_0^t T(t-\tau)u(\tau)d\tau = \sum_{n=1}^{+\infty} \int_0^t e^{\lambda_n(t-\tau)} v_n(x) \langle v_n, u(\tau) \rangle d\tau$$

Input-Output maps

$$\Psi_t(t) = A\Psi(t) + Bu(t)$$

$$\phi(t) = C\Psi(t)$$

Input-output mapping

$$\phi(t) = [H u](t) = \int_0^t C T(t-\tau) B d\tau$$

* Impulse response

$$H(t) = (C^T(t)^T B) \mathbb{1}(t)$$

* Transfer function

$$H(s) = C(sI - A)^{-1} B$$

* Frequency response

$$H(j\omega) = C(j\omega I - A)^{-1} B$$

An example

$$\begin{aligned} \dot{\phi}_t(x, t) &= \dot{\phi}_{xx}(x, t) + d_t(t) \\ \phi(\pm 1, t) &= 0 \end{aligned} \quad \xrightarrow{\text{Laplace transform}} \quad \begin{cases} \dot{\phi}(x, s) = s\phi(x, s) - d(x, s) \\ \phi(\pm 1, s) = 0 \end{cases}$$

$$\begin{bmatrix} \dot{\psi}_1(x, s) \\ \dot{\psi}_2(x, s) \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ s & 0 \end{bmatrix} \begin{bmatrix} \psi_1(x, s) \\ \psi_2(x, s) \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} d(x, s)$$

$$\phi(x, s) = [1 \ 0] \begin{bmatrix} \psi_1(x, s) \\ \psi_2(x, s) \end{bmatrix}$$

$$0 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \psi_1(-1, s) \\ \psi_2(-1, s) \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} \psi_1(1, s) \\ \psi_2(1, s) \end{bmatrix}$$

Two point boundary value problems

$$\dot{\psi}(x) = A(x) \psi(x) + B(x) d(x)$$

$$\psi(x) = C(x) \Psi(x)$$

$$0 = N_a \psi(a) + N_b \psi(b)$$

For boundary inputs

$$\dot{\phi}_t(x, t) = \dot{\phi}_{xx}(x, t) + d(x, t)$$

$$\phi(-1, t) = u(t)$$

$$\phi(+1, t) = 0$$

Problem : control does not enter additively into the equation

Define :

$$\Psi(x, t) = \phi(x, t) - f(x) u(t)$$

$$\phi(x=-1, t) = u(t)$$

$$\phi(x=+1, t) = 0$$

determine $f(x)$ s.t.

$$\Psi(x=\pm 1, t) = 0$$

$$\Psi(-1, t) = \phi(-1, t) - f(-1) u(t) = u(t) - f(-1) u(t) \stackrel{\text{want}}{=} 0 \iff f(-1) = 1$$

$$\Psi(1, t) = \phi(1, t) - f(1) u(t) = 0 - f(1) u(t) \stackrel{\text{want}}{=} 0 \iff f(1) = 0$$

Many choices for $f(x)$, for example, $\boxed{f(x) = \frac{1-x}{2}}$

In new coordinates,

$$\Psi_t(x, t) + f(x) \dot{u}(t) = \Psi_x(x, t) + f''(x) u(t) + d(x, t)$$

$$\Psi(\pm 1, t) = 0$$

New input: $v(t) = \dot{u}(t)$

$$\frac{d}{dt} \begin{bmatrix} \Psi(t) \\ u(t) \end{bmatrix} = \begin{bmatrix} A_0 & f'' \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \Psi(t) \\ u(t) \end{bmatrix} + \begin{bmatrix} I \\ 0 \end{bmatrix} d(t) + \begin{bmatrix} -f \\ I \end{bmatrix} v(t)$$

$$\phi(t) = [I \quad f] \begin{bmatrix} \Psi(t) \\ u(t) \end{bmatrix}$$

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Note : Curtain's book (More general)

$$\phi_t = A\phi$$

$\epsilon\phi(t) = u(t)$, point evaluation functional

$$[\epsilon] \begin{bmatrix} \phi(t) \end{bmatrix} = u(t)$$

Right inverse of ϵ

$\epsilon F = I$, in our example, we select $F = f(x)$, $f(-1) = 1$, $f(+1) = 0$

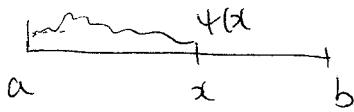
$$\epsilon F \cdot u(t) = u(t)$$

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Two point boundary value problems

$$\psi' = A\psi + Bd \quad \dots \text{ (1)}$$

$$Y = N_a \psi(a) + N_b \psi(b) \quad \dots \text{ (2)}$$



$$\psi(x) = e^{A(x-a)} \underbrace{\psi(a)}_{\text{unknown!}} + \int_a^x e^{A(x-\xi)} Bd(\xi) d\xi \quad \dots \text{ (3)}$$

evaluation (3) at $x=b$ and plug into (2)

$$\Rightarrow Y = \underbrace{\left[N_a + N_b e^{A(b-a)} \right]}_{\text{If invertible, then } \psi(a) = f(Y, d)} \psi(a) + N_b \int_a^b e^{A(b-\xi)} Bd(\xi) d\xi$$