

Fourier Transform : \mathcal{F}

09-20-11

$$L_2(-\infty, \infty) \supset \mathcal{D}(\mathcal{d}) \xrightarrow{\mathcal{d} = \frac{\partial^2}{\partial x^2}} L_2(-\infty, \infty)$$

$$\mathcal{F} \begin{array}{c} \uparrow \\ \downarrow \end{array}$$

$$\begin{array}{c} \uparrow \mathcal{F}^{-1} \\ \downarrow \end{array}$$

$$L_2(-\infty, \infty) \supset \mathcal{D}(\hat{\mathcal{d}}) \xrightarrow[\text{multiplication operator}]{\hat{\mathcal{d}}(k) = -k^2} L_2(-\infty, \infty)$$

F.T. brings $\phi_t = \phi_{xx} + u$ to

$$\hat{\phi}(k, t) = -k^2 \hat{\phi}(k, t) + \hat{u}(k, t)$$

Continuum of decoupled scalar states
(parameterized by $k \in \mathbb{R}$)

↓
wave-number

F.T. "diagonalizes" generator of our dynamics

$$\text{L.i.e. operator } \mathcal{d} = \frac{d^2}{dx^2} \Big|_{L_2(-\infty, \infty)}$$

Heat equation

$$\phi_t = \phi_{xx} \quad \text{with B.C. } \phi(x = \pm 1, t) = 0$$

$$\text{I.C. } \phi(x, t=0) = f(x)$$

$$\phi(x, t) = \sum_{n=1}^{\infty} a_n(t) v_n(x)$$

$$\langle v_n, v_m \rangle = \int_{-1}^1 v_n^*(x) v_m(x) dx = \delta_{m,n} = \begin{cases} 1 & m=n \\ 0 & m \neq n \end{cases}$$

Cont'd →

$$\sum_{n=1}^{\infty} \dot{\alpha}_n(t) v_n(x) = \sum_{n=1}^{\infty} \alpha_n(t) v_n''(x)$$

Use the fact that

$$v_n''(x) = \lambda_n v_n(x)$$

$$\sum_{n=1}^{\infty} \dot{\alpha}_n(t) v_n(x) = \sum_{n=1}^{\infty} \lambda_n \alpha_n(t) v_n(x)$$

$$\langle v_m, \sum_{n=1}^{\infty} \dot{\alpha}_n(t) v_n(x) \rangle = \langle \cancel{v_m}, \sum_{n=1}^{\infty} \lambda_n \alpha_n(t) v_n(x) \rangle$$

$$\sum_{n=1}^{\infty} \dot{\alpha}_n \underbrace{\langle v_n, v_m \rangle}_{\delta_{n,m}} = \sum_{n=1}^{\infty} \lambda_n \alpha_n(t) \underbrace{\langle v_n, v_m \rangle}_{\delta_{n,m}}$$

$$\boxed{\dot{\alpha}_m(t) = \lambda_m \alpha_m(t)}$$

Eigen-function expansion brings

$$\begin{cases} \Phi_t = \Phi_{xx} \\ \Phi(\pm 1, t) = 0 \end{cases} \text{ into}$$

$$\frac{d}{dt} \begin{bmatrix} \alpha_1(t) \\ \alpha_2(t) \\ \vdots \end{bmatrix} = \begin{bmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \ddots \end{bmatrix} \begin{bmatrix} \alpha_1(t) \\ \alpha_2(t) \\ \vdots \end{bmatrix}$$

$$L_2[-1,1] \supset \mathcal{D}(\hat{c}) \xrightarrow{\hat{c} = \frac{d^2}{dx^2}} L_2[-1,1]$$

Basis expansion

$$l_2(\mathbb{N}) \supset \mathcal{D}(\hat{c}) \xrightarrow[\text{multiplication operator}]{\hat{c} = \text{diag}\{\lambda_n\}_{n \in \mathbb{N}}} l_2(\mathbb{N})$$

Remaining Task

Find dependence of

$a_n(0)$ on $\phi(x,0) = f(x)$

initial condition

So far : $\phi(x,t) = \sum_{n=1}^{\infty} e^{\lambda_n t} a_n(0) v_n(x)$

$$f(x) = \phi(x,0) = \sum_{n=1}^{\infty} a_n(0) v_n(x)$$

$$\langle v_m, f \rangle = \sum_{n=1}^{\infty} a_n(0) \langle v_m, v_n \rangle$$

$\underbrace{\langle v_m, v_n \rangle}_{\delta_{m,n}}$

$$a_m(0) = \langle v_m, f \rangle$$

Then,

$$\begin{aligned} \phi(x,t) &= \sum_{n=1}^{\infty} e^{\lambda_n t} v_n(x) \langle v_n, f \rangle \\ &= \sum_{n=1}^{\infty} e^{\lambda_n t} v_n(x) \int_{-1}^1 v_n^*(\xi) f(\xi) d\xi \\ &= \int_{-1}^1 \sum_{n=1}^{\infty} e^{\lambda_n t} v_n(x) v_n^*(\xi) f(\xi) d\xi \end{aligned}$$

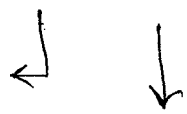
$\underbrace{\hspace{10em}}_{T(x, \xi, t)}$

$$\phi(x,t) = \int_{-1}^1 T(x, \xi, t) f(\xi) d\xi$$

Abstractly

$$\phi(x, t) = [T(t) \cdot \dagger](x)$$

propagator of the
dynamics



initial condition

$T(t)$ is an operator with a kernel
representation $T(x, \xi, t)$

Finite dimensional ↓

$$\boxed{\frac{d\psi}{dt} = A\psi} \quad (1)$$

$$A = V\Lambda V^* \iff V^*AV = \Lambda$$

introduce a coordinate transformation:

$$\phi = V^* \psi \longrightarrow \begin{bmatrix} \phi_1 \\ \vdots \\ \phi_n \end{bmatrix} = \begin{bmatrix} v_1^* \\ \vdots \\ v_n^* \end{bmatrix} \begin{bmatrix} \psi_1 \\ \vdots \\ \psi_n \end{bmatrix}$$

$$\psi = V^{-*} \phi = V \Phi$$

$$V^* \left(V \frac{d\phi}{dt} = AV\phi \right) \Rightarrow$$

$$V^* V \frac{d\phi}{dt} = V^* AV \phi \Rightarrow \boxed{\frac{d\phi}{dt} = \Lambda \phi}$$

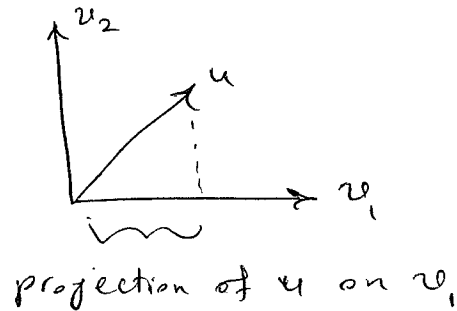
$$\begin{array}{ccc} \psi \in \mathbb{R}^n & \xrightarrow{A} & \mathbb{R}^n \\ \downarrow V^* & & \uparrow \\ \phi \in \mathbb{R}^n & \xrightarrow{\Lambda = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}} & \mathbb{R}^n \end{array}$$

$$\Rightarrow \psi(t) = e^{At} \psi(0)$$

Summary

$$A u = \sum_{i=1}^n \lambda_i v_i \underbrace{\langle v_i, u \rangle}_{\text{Projection of } u \text{ on } v_i}$$

for $u \in \mathbb{R}^2$



Then,
$$e^{At} u = \sum_{i=1}^n e^{\lambda_i t} v_i \langle v_i, u \rangle \quad (1)$$

Note: if $u = v_m$

$$\begin{aligned} e^{At} u &= e^{At} v_m = \sum_{i=1}^n e^{\lambda_i t} v_i \underbrace{\langle v_i, v_m \rangle}_{\delta_{i,m}} \\ &= e^{\lambda_m t} \cdot v_m \end{aligned}$$

In the case of Heat equation

$$\phi(x,t) = \sum_{n=1}^{\infty} e^{\lambda_n t} \cdot v_n(x) \langle v_n, f \rangle \quad (2)$$

(1) & (2) are conceptually similar.

The main difference ~~is~~ is the inner-product that is used in (1) or (2).